## $>$ High on control big on reliability



L×2000 AC Drive for Elevator

Three Phase 230V (2.2 ~ 37kW)
Three Phase $415 \mathrm{~V}(2.2 \sim 45 \mathrm{~kW})$

## Two decades of application knowledge

For over two decades, various industry sectors have been reaping the benefits of L\&T's cost-effective, performance-oriented AC Drive solutions. L\&T's grasp of the specific needs of each industry enables it to offer application-specific solutions for various industries - such as processing, textile, plastic, ceramic, pharmaceutical, elevator, oil \& gas, power, cement and material-handling.


## Ľ2000 AC Drive

## The new level of reliability



It handles loads up to 45 kW , and is engineered to keep your elevator operating at optimum efficiency, even in the hot,
humid and dusty conditions that characterise harsh environment.


## Backed by engineering knowledge across seven decades

A knowledge-based company, L\&T brings you the benefits of over 75 years of engineering experience and expertise, and the richness of its collaborations with technology leaders across the globe.

For 50 years, L\&T's low-tension switchgear - India's widest range - has been the preferred option of top industrial houses countrywide.

## Meeting your needs, solving your problems

We believe in addressing your needs and not just selling a product. That's why a dedicated Solutions Team first focuses on understanding your application. Then helps you select the drive that best meets your needs. Our advice on installation, maintenance and replacement will ensure that your elevators function at peak productivity. From engineer to repair technician, our people have the knowledge and skill-sets to deliver total peace of mind.




## Tested. Certified. Reliable.

L\&T is one of the few switchgear manufacturers in India with a dedicated, NABL-certified testing facility. Our products are tested for conformity to standards that exceed minimum requirements, giving you the assurance of high-quality performance. Our focus on continuous improvement ensures that our standards are on par with the best in the world. Repeat orders endorse the value that we deliver.

## After-sales service aimed at maximum uptime

A malfunction of the drive can bring an elevator to a halt. To ensure maximum uptime for you, our Rapid Response service team is available to analyze the situation and help you set the problem right. We have set up strategic service centres across the country to provide temporary replacement drives or ready spares to ensure that your business keeps running smoothly.



## Training your people to enhance your operations

At our countrywide Switchgear Training Centres, we can train your operators, electricians and supervisors to increase their effectiveness in the operation and maintenance and trouble-shooting of your drives. We can also conduct in-plant training and workshops at your premises to improve both power management and equipment maintenance skills. This gives you total operational excellence, minimising downtime.

L\&T's engineers and channel partners also upgrade their skills through seminars, workshops, training sessions and white papers on electrical practices.

# Features that ensure performance 

- Suitable for geared / gearless machines
- Compatibility with various types of encoders
- Anti-roll-back algorithm
- Load and direction based floor-leveling
- Built-in ARD function
- Conformal Coating as per IEC 60721-3-3 class 3C2


## L×2000

## Provides Dedicated Solutions for Elevator Systems

Controls the elevator system smoothly and efficiently

Lx2000 guarantees stable driving and monitoring of the elevator with both optimum speed pattern and position control.


Time Chart for Anti-Rollback Function


Before Anti-Rollback Algorithm


[^0]

## Auto-tuning

Standstill auto-tuning
L\&T's unique technology allows auto-tuning to be performed even with the motor shaft directly connected to the load. Standstill auto-tuning is useful for elevators because it does not require removal of the brake coupling connected to the motor.

Rotationel auto-tuning
Widely used for vector-control drives, this requires
the motor shaft to be free from the coupling for proper operation.

## Built-in brake control for safe vertical loading

To minimize risk of the elevator's giving in to the gravitational pull of the earth, brake-control is built-in.


## Extreme precise control

The SIN/COS encoder option enables more precise control over a normal encoder.


## SPM, IPM motor control

## SIN/COS encoder option

With synchronous motor initial stimulus position estimation, the Lx2000 perfectly controls the SPM and IPM motor.

- SPM, IPM motor
- 30,000 rpm driving fast response within 100 msec


The actual angle
The estimated angle


## User-Friendly Interface

Easy-to-use with user-centric keypad and removable terminal blocks

Supports communication devices such as Modbus-RTU,
CC-Link

Systematic and efficient system management through DriveConnet 2.0


Easy-to-maintain drive/motor parameter via PC

## PC-based Software for Easy Maintenance of Drive and Motor Parameters

DriveConnect software allows drive/system monitoring on a PC and easy maintenance of drive and motor parameters

- Windows-based graphic user interface (GUI]
- Modbus-RTU
- Connecting up to 31 drives
- Integrated control console
- Offline editing function
- Data upload/download
- 4-channel oscilloscope
- Trigger function


User-Friendly Design


## Easy-to-use keypad

By adopting a user-centered operation keypad, parameter setting becomes easier. When applying to the system, the varied information required can be monitored.


## International standard removable terminal block

Wiring and maintenance is made easy by an international standard acquired terminal block.

- DriveConnect

Drive Connect


## - Reporting 1



- Drive integrated console

- Reporting 2

- Parameter management



## - Oscilloscope/Trigger




| LTVF | L |  | 4 | 0012 | A |  | A | A |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L\&T <br> Variable <br> Frequency Drive | Series | Input Voltage |  | Drive Current Rating | Enclosure |  | Reserved | Reserved |
|  | Lx2000 | 2 | Three-Phase 200~240[V] | Drive Rated Current | A | IPOO |  |  |
|  |  | 4 | Three-Phase 380~480[V] |  |  |  |  |  |



- Data and status display


## MODE

- Shift between function groups
- Shifting from group code to the upper code
- Function code shift
- Shift to next function code
- Data increase in set up mode


## REV•

- Reverse run command key
- Only available, with loader operation
- LED is turned ON with reverse run
- Blinks during Acc/Deceleration of reverse run
- Shift to function code
- Shift to previous code
- Data is decreased in set up mode


## PROG

- Data set up start

ENT

- Data set up completion


## SHIT

- Decimal point shift
- Only available in case of data setup


## FWD •

- Forward run command key
- Only available with loader operation
- LED is turned on with forward operation
- Blinks during Acc/Deceleration of forward operation


## STOP <br> RESET

- Stop command
- Available with the loader operation
- LED is turned on when drive stops its operation
- Blinks when fault occurs
- Reset
- Fault reset


## Digital Operator Instructions

| Classification | Display | Function Name | Function |
| :---: | :---: | :---: | :---: |
| KEY | MODE <br> PROG <br> ENT <br> $\Delta$ (up) <br> V (down) <br> Shift/ESC <br> REV <br> STOP/RESET <br> FWD | Mode Key <br> Program Key <br> Enter Key <br> Up Key <br> Down Key <br> Shift/ESC Key <br> Reverse run <br> Stop/Reset Key <br> Forward Key | Shift between groups. <br> Shift from a group code to upper code. <br> Parameter setting value change. <br> Saving altered setting values. <br> Shift between codes and increase the parameter value. <br> Shift between codes and decrease the parameter value. <br> In case of set-up mode, it is operated with the shift key. Operation with ESC key in <br> non-set up mode. <br> Reverse run key. <br> Stop key when drive is on operation. <br> Forward run key. |
| LED | (REV) <br> (STOP/RESET) <br> (FWD) | Reverse run key <br> Stop/Fault display <br> Forward Run Display | Turns on at reverse operation. <br> Blinks while the drive is on Acc/Deceleration and then turns on the constant speed operation. <br> Turns off when drive stops operation. <br> Blinks when fault occurs. <br> Turns on during forward operation. <br> Acc/Deceleration running modes blink the lamp and it is turned on in the forward operation. |

Input and Output Specification: Input Voltage Three-Phase 230V

| LTVF-L2 $\square \square \square \square$ AAA |  | 0012 | 0016 | 0024 | 0032 | 0046 | 0059 | 0074 | 0088 | 0122 | 0146 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Maximum applicable motor ranges ${ }^{1)}$ | HP | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 |
|  | kW | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 |
| Rated output | Capacity [kVA] | 4.5 | 6.1 | 9.1 | 12.2 | 17.5 | 22.5 | 28.2 | 33.1 | 46 | 55 |
|  | Rated current [ A ] | 12 | 16 | 24 | 32 | 46 | 59 | 74 | 88 | 122 | 146 |
|  | Output frequency | $0-120 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |
|  | Output voltage | $0 \sim 200 \mathrm{~V}(230 \mathrm{~V})^{2)}$ |  |  |  |  |  |  |  |  |  |
| Rated input | Voltage | 3Phase 200~230V (-10\% ~ +10\%) |  |  |  |  |  |  |  |  |  |
|  | Frequency | $50 \sim 60 \mathrm{~Hz}( \pm 5 \%)$ |  |  |  |  |  |  |  |  |  |
| Overload Tolerance |  | 150\% of rated current for 60 sec . |  |  |  |  |  |  |  |  |  |
| Dynamic Braking Unit |  | Built-in |  |  |  |  |  |  |  | External (option) |  |

Input and Output Specification: Input Voltage Three-Phase 415V

| LTVF-L4 $\square \square \square \square$ AAA |  | 0006 | 0008 | 0012 | 0016 | 0024 | 0030 | 0039 | 0045 | 0061 | 0075 | 0091 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Maximum applicable motor ranges ${ }^{1)}$ | HP | 3 | 5 | 7.5 | 10 | 15 | 20 | 25 | 30 | 40 | 50 | 60 |
|  | kW | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 |
| Rated output | Capacity [kVA] | 4.5 | 6.1 | 9.1 | 12.2 | 18.3 | 22.9 | 29.7 | 34.3 | 46 | 57 | 70 |
|  | Rated current [A] | 6 | 8 | 12 | 16 | 24 | 30 | 39 | 45 | 61 | 75 | 91 |
|  | Output frequency | $0-120 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |
|  | Output voltage | $0 \sim 380 \mathrm{~V}(480 \mathrm{~V})^{2)}$ |  |  |  |  |  |  |  |  |  |  |
| Rated input | Voltage | 3Phase $380 \sim 480 \mathrm{~V}(-10 \% \sim+10 \%)$ |  |  |  |  |  |  |  |  |  |  |
|  | Frequency | $50 \sim 60 \mathrm{~Hz}( \pm 5 \%)$ |  |  |  |  |  |  |  |  |  |  |
| Overload Tolerance |  | $150 \%$ of rated current for 60 sec . |  |  |  |  |  |  |  |  |  |  |
| Dynamic Braking Unit |  | Built-in |  |  |  |  |  |  |  |  | External (option) |  |


| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
| Circuit type |  |  | Circuit type |
| Control | Control type <br> Frequency / Speed <br> Control accuracy <br> Frequency / Speed <br> Resolution |  | Open Loop Vector, Closed Loop Vector \& Closed Loop Vector PM <br> Analog: $\pm 0.2 \%$ of maximum command speed $\left(25 \pm 10^{\circ} \mathrm{C}\right)$ <br> Digital: $\pm 0.01 \%$ of maximum command speed $\left(0 \sim 40^{\circ} \mathrm{C}\right)$ <br> Analog: $\pm 0.05 \%$ of maximum command speed <br> Digital: $0.01 \%$ of maximum command speed |
|  | Vector <br> Speed <br> ACC/DEC | Response speed <br> Torque control <br> Torque Boost <br> Time setup <br> Combination <br> Pattern | 50 Hz <br> 3\% <br> Manual torque boost ( $0-20 \%$ ), Automatic torque boost 6000.0 sec (Time unit can be set) <br> 4 combined of Acc/Deceleration time <br> Linear, S-Curve |
| Braking | Braking type <br> Braking torque <br> Braking resistor |  | Dynamic braking using external resistor 150\% <br> An external braking resistor is required |
| Input | Spe <br> An <br> Dig |  | Digital setting <br> Multi-step-speed setup by digital input <br> Analog input setting of $-10 \sim 10 \mathrm{~V}$ or $4 \sim 20 \mathrm{~mA}$ <br> Setting by options <br> 3-Channels (Al1, Al2, Al3) <br> $-10 \sim 10 \mathrm{~V}, 4 \sim 20 \mathrm{~mA}, 10 \sim 0 \mathrm{~V}, 20 \sim 4 \mathrm{~mA}$, motor NTC (selectable) <br> Selectable among 9 different multi-function analog inputs <br> FX, RX, BX, RST, P1 ~ P7 <br> Multi-function input terminal (P1~P7) can be selected among various functions. |
| Output | Analog output |  | 2-Channel (A01, A02) <br> $-10 \sim 10 \mathrm{~V}$ output <br> Selective among 31 multi-function analog output functions <br> Multi function digital output: 2 channels (1A-1B, 2A-2B) <br> Fault digital output: 1 channel (30A-30C, 30B-30C) <br> 1 channel (OCI/EG) |
| Protection function |  |  | Over-current, overllow voltage, drive overheat, drive thermal sensor open, motor over-heat, motor thermal sensor open, over speed, IGBT gate blocking (BX), fuse open, trip by unusual external signal, encoder error, communication error, electronic thermal, stall prevention (V/F), over load(V/F), drive over load. |
| Environment |  | environment <br> perature <br> midity <br> hod <br> bation | Indoor, free of corrosive gas and direct sunlight <br> o-10~40 C (Non-frozen condition) <br> Below RH 90\% (Dew-free) <br> Forced cooling by FAN <br> Below 1000 meters / above sea level $5.9 \mathrm{~m} / \mathrm{s}^{2}(=0.6 \mathrm{G})$ |

## 2.2~22kW (230/415V)



## $30 \sim 37 \mathrm{~kW}(230 \mathrm{~V}) \& 30 \sim 45 \mathrm{~kW}$ (415V)



Input and Output Specification: Input Voltage Three-Phase 230V

| Display | Name | Description |
| :--- | :--- | :--- |
| R, S, T | AC Input | 3Phase AC input connection |
|  |  | 1) $230 \mathrm{~V}: 200 \sim 230 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ |
|  |  | 2) $415 \mathrm{~V}: 380 \sim 480 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ |
| U, V, W | Output | Cable connection of 3 phase induction motor |
| G | Earth | Drive frame earth terminal |
| B1, B2 | Braking resistor | Braking resistor connection |
| P1, P2 reactor and Braking unit | DC reactor, braking unit and DC link common connection terminal |  |
| P | DC Link(-) terminal | DC Link common connection terminal |
| N |  | Braking unit and DC link common terminal |

Control Circuit Terminals

| Item | Display | Name | Description |
| :---: | :---: | :---: | :---: |
| Digital input | FX <br> RX <br> RST <br> P1(MMO) <br> CM <br> VREF | Forward run command <br> Reverse run command <br> Fault reset <br> Common | - ON when tied to CM terminal <br> - Stops when FX and RX are ON/OFF simultaneously <br> - Clears the fault condition only when the fault state is removed <br> - Selectable among the following functions: <br> (Multi step speed selection $1 / 2 / 3$, JOG run, MOP up/down/Save/Clear, analog hold, main drive, speed acc/dec time selection, 3 -wire operation, external default signal B contact point, timer input, soft-start cancellation, ASR PI gain selection, ASR P.PI selection, pre-excitation, torque bias <br> - ON in case of connection b etween CM and digital |
| Analog input | Al1 <br> AI2 | Analog setting power <br> Voltage input <br> Current input | - V ariable resistor use standard voltage ( +10 V ):10 0 <br> - Voltage input (-10~10V), current input ( $4 \sim 20 \mathrm{~mA}$ ) <br> The motor NTC input is selectable <br> - Selectable among following functions; (Speed reference, Torque bias, Torque limit, Process PI control reference, Motor NTC input) <br> - Jumper set up use AC voltage input <br> $\rightarrow$ Al1, AI2: Open , Al3:Left of switch |
|  | AI3 | Voltage input Motor NTC input | - Jumper set to use as voltage input <br> $\rightarrow$ Al1,AI2: Short <br> - With motor NTC input, switch direction setup <br> $\rightarrow$ AI3: Right of switch |
|  | 5G | COMMON | - Analog input COMMON terminal |

## Control Circuit Terminals

| Classification | Display | Name | Description |
| :---: | :---: | :---: | :---: |
| Encoder <br> Input | PE <br> 5G <br> A+ <br> A- <br> B+ <br> B- <br> PE <br> 5G <br> PA <br> PB | Encoder power <br> Encoder A phase signal <br> Encoder B phase signal <br> Encoder power <br> Encoder A phase signal <br> Encoder B phase signal | +5 V Line drive power (Jumper set required) <br> OV <br> - A and B phase signals of line drive encoder <br> - T o use the line drive type encoder, the 'P5 pin' of I/O PCB JP2 should be shorted and then the JP1 switch should be pulled down to 'LD' direction <br> - Jumper set-up (factory default) <br> +15 V Open collector power (Jumper set-up is required) <br> OV <br> - A and B phase signals of complementary and open collector type signals <br> - Short the 'P15 pin' of I/O PCB JP2 and then pull up the JP1 switch to 'OC' |
| Encoder output | RA <br> GE <br> RB <br> GE | Encoder output-phase A <br> Encoder output common terminal <br> Encoder output-phase B <br> Encoder output common terminal | - Encoder phase A and B output signal (Open collector type) |
| Analog <br> Output | A01 <br> AO2 <br> 5G | Analog output1 <br> Analog output2 <br> COMMON | - Output -10V~+10V <br> - Select from among the following 31 items: (motor speed, speed reference1~2, Torque reference1 $\sim 2$, Torque current volume flux reference, flux reference volume, drive output current, drive output voltage, Motor temperature, DC voltage) <br> - COMMON terminal for analog output |
| Digital <br> Output | 1A <br> 1B <br> 2A <br> 2B <br> OC1 <br> EG <br> 30A <br> 30B <br> 30C | Multi-function digital output1 (contact point A) <br> Multi-function digital output2 <br> (contact point B) <br> Multi-function open collector output <br> Fault signal A contact point <br> Fault signal B contact point <br> COMMON | - Select from among the following 14 items: (zero speed detection, speed detection (polarity valid), speed detection (rotation direction invalid), speed reach, speed matching, arbitrary torque detection torque limit feature, motor overheating signal, drive overheating signal, low voltage feature, drive run signal, drive regeneration signal, drive run function, timer output) <br> - Activates when the faults occur <br> - Not available in emergency stop <br> - Common for A and B digital output |

## Control Circuit Terminal

## Control Terminal Feature

- Control Terminal Panel Arrangement(Standard Type(SIO) - Non insulated type)
$\begin{array}{llllllllll} & B & C & 1 A & 1 B & 2 A & 2 B & 3 A & 3 B\end{array}$


FX RX BX RST CM P1 P2 P3 P4 P5 P6 P7 CM


VRF Al1 Al2 Al3 5G A01 A02 5G PWR 5G A+ A- B+ BNTC

## Various Optional Cards

Synchronous option, SIN/COS encoder option, expansion I/O,
Elevator dedicated I/O, etc.

CC Link Option Card (LTCI-CCL-L)

- Max. 10 Mbps speed
- Customized LS profile
- CC Link customized cable
- Built-in termination resistor
- Remote I/O : each 32 point
- Remote register : 4 words


## Distance Control Card (LTEL-EIO-L)

- Position sensor/safety switch input
- Car position output
- E/L position and sequence control
- MC/Brake operation signal output
- E/L exclusive connector


## SIN/COS ENCODER (LTEN-SCE-L)



## Braking resistor specifications

Resistance values in the table shown below are calculated based on the 150\% braking torque, 10\%ED* standard.

| Input Voltage | Drive Cat. No. | Capacity (10\%ED) |  |
| :---: | :---: | :---: | :---: |
|  |  | [ $\Omega$ ] | [W] |
| Three-Phase 230V | LTVF-L20012AAA | 50 | 800 |
|  | LTVF-L20016AAA | 33 | 1200 |
|  | LTVF-L20024AAA | 20 | 1600 |
|  | LTVF-L20032AAA | 15 | 2400 |
|  | LTVF-L20046AAA | 10 | 4800 |
|  | LTVF-L20059AAA | 8 | 4800 |
|  | LTVF-L20074AAA | 5 | 7200 |
|  | LTVF-L20088AAA | 5 | 7200 |
| Three-Phase 415V | LTVF-L40006AAA | 200 | 800 |
|  | LTVF-L40008AAA | 130 | 1200 |
|  | LTVF-L40012AAA | 85 | 1600 |
|  | LTVF-L40016AAA | 60 | 2400 |
|  | LTVF-L40024AAA | 40 | 4800 |
|  | LTVF-L40030AAA | 30 | 4800 |
|  | LTVF-L40039AAA | 20 | 7200 |
|  | LTVF-L40045AAA | 20 | 7200 |

-     * \% ED is based on 100 sec .


## Brake resistor wiring

For brake resistor with a temperature detection sensor for fire protection, refer below when in use.

| Brake resistor terminal blocks | Drive terminals | Operation |
| :---: | :---: | :---: |
| B1, B2 | P,BR |  |
| P7, CM | One of the multi-function input terminals, <br> out of $P 1 \sim P 7$, of control terminals board is <br> used as defining 'External trip signal contact $B^{\prime}$ | The contact is ON in normal temperature and <br> opens in overheat. |

## Braking Unit LED Functions

| Displayed Item | Description |
| :--- | :--- |
| POWER | Main power in braking unit turns on the POWER LED. Generally the braking unit is wired to the drive, so <br> once the input main power of drive is on, the POWER LED of braking unit turns on. |
| RUN | While braking unit operates its normal operation by the motor regenerative energy, <br> the RUN LED blinks. |
| OHT | During the braking operation, if the braking unit heat sink is overheated and exceeds its limited value, <br> the overheat protection function operates. <br> This blocks the braking unit signal and then turns on the OHT LED. |
| OCT | During the braking operation, if over-current flows in the main circuit of braking unit then the over <br> current protection function is operated in order to prevent the circuit from over current. |
| The TURN ON signal of braking unit is blocked and then turns on the OCT LED. |  |

## Terminal Block and Braking Unit



Main circuit terminal block Control circuit terminal



IN+ IN- OUT+ OUT- 30B 30C 30A

## Terminal Block and Braking Unit



Double use of Braking Unit


## Combination of Braking Units and Braking Resistors

- 30~37kW (230V/415V)

- 45kW (415V)



## MCCB (Moulded Case Circuit Breaker) and MC (Magnetic Contactor)

| Input Voltage | Motor (kW) | Drive Cat. No. | MCCB (L\&T) | MC (L\&T) |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Three-Phase } \\ & 230 \mathrm{~V} \end{aligned}$ | 2.2 | LTVF-L20012AAA | DM100/30 | MO 18 |
|  | 3.7 | LTVF-L20016AAA | DM100/30 | MO 32 |
|  | 5.5 | LTVF-L20024AAA | DM100/50 | MO 50 |
|  | 7.5 | LTVF-L20032AAA | DM100/60 | MO 50 |
|  | 11 | LTVF-L20046AAA | DN2-250M/100 | M0 70 |
|  | 15 | LTVF-L20059AAA | DN2-250M/125 | MO 95 |
|  | 18.5 | LTVF-L20074AAA | DN2-250M/160 | MNX 140 |
|  | 22 | LTVF-L20088AAA | DN2-250M/160 | MNX 140 |
|  | 30 | LTVF-L20122AAA | DN2-250M/250 | MNX 140 |
|  | 37 | LTVF-L20146AAA | DN3-400M/320 | MNX 225 |
| $\begin{gathered} \text { Three-Phase } \\ 415 \mathrm{~V} \end{gathered}$ | 2.2 | LTVF-L40006AAA | DM16/16 | M0 12 |
|  | 3.7 | LTVF-L40008AAA | DM16/16 | MO 18 |
|  | 5.5 | LTVF-L40012AAA | DM100/30 | MO 25 |
|  | 7.5 | LTVF-L40016AAA | DM100/30 | MO 32 |
|  | 11 | LTVF-L40024AAA | DM100/50 | MO 50 |
|  | 15 | LTVF-L40030AAA | DM100/60 | MO 50 |
|  | 18.5 | LTVF-L40039AAA | DM100/80 | MO 70 |
|  | 22 | LTVF-L40045AAA | DN2-250M/100 | MO 70 |
|  | 30 | LTVF-L40061AAA | DN2-250M/125 | MO 95 |
|  | 37 | LTVF-L40075AAA | DN2-250M/160 | MNX 140 |
|  | 45 | LTVF-L40091AAA | DN2-250M/160 | MNX 140 |

## 2.2 ~ 22kW (230V/415V)



| Input Voltage | Drive Cat. No. | W (mm) | H (mm) | D (mm) | Weight (kg) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { Three-Phase } \\ 230 \mathrm{~V} \end{gathered}$ | LTVF-L20012AAA | 200 | 284 | 207 | 6 |
|  | LTVF-L20016AAA | 200 | 284 | 207 | 6 |
|  | LTVF-L20024AAA | 200 | 284 | 207 | 14 |
|  | LTVF-L20032AAA | 200 | 355 | 202 | 14 |
|  | LTVF-L20046AAA | 200 | 355 | 202 | 13.7 |
|  | LTVF-L20059AAA | 250 | 385 | 221 | 13.7 |
|  | LTVF-L20074AAA | 250 | 385 | 221 | 20.3 |
|  | LTVF-L20088AAA | 304 | 460 | 254 | 20.3 |
| $\begin{gathered} \text { Three-Phase } \\ 415 \mathrm{~V} \end{gathered}$ | LTVF-L40006AAA | 200 | 284 | 207 | 6 |
|  | LTVF-L40008AAA | 200 | 284 | 207 | 6 |
|  | LTVF-L40012AAA | 200 | 355 | 202 | 14 |
|  | LTVF-L40016AAA | 200 | 355 | 202 | 14 |
|  | LTVF-L40024AAA | 250 | 385 | 221 | 13.7 |
|  | LTVF-L40030AAA | 250 | 385 | 221 | 13.7 |
|  | LTVF-L40039AAA | 304 | 460 | 254 | 20.3 |
|  | LTVF-L40045AAA | 304 | 460 | 254 | 20.3 |

## 2.2 ~ 22kW (230V/415V)

| Input Voltage | Drive Cat. No. | $\mathbf{W}(\mathbf{m m})$ | $\mathbf{H}(\mathbf{m m})$ | D (mm) | Weight (kg) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Three-Phase | LTVF-L20122AAA | 350 | 680 | 308.2 |  |
| 230V | LTVF-L20146AAA | 350 | 680 | 308.2 | 42 |
| Three-Phase <br> 415V | LTVF-L40061AAA | 350 | 680 | 308.2 | 42 |
|  | LTVF-L40075AAA | 350 | 680 | 308.2 | 42 |
|  | LTVF-L40091AAA | 375 | 780 | 326 | 42 |

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[^0]:    Green : Posion Error between Command \& Actual Spd.

